

# Modal Design Envelope for RAM Mixing

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## Problem Statement

The RAM5 Pedestal is a highly versatile platform for MIC and other mixing configurations



Overhead Clamp   Mix in Case   Oversized   Continuous   Development   Custom

**This versatility increases the risk of machine or vessel failure when designing for the RAM environment!**



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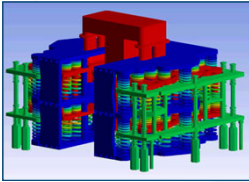
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## Most Significant Risk: Off-Axis Modes

- A Resonant Mode is the type of motion a vibrating body undergoes on its natural frequency
- The primary Resonant Mode for RAM Technology is vertical displacement
- RAM Equipment is designed for 100g operation on this mode



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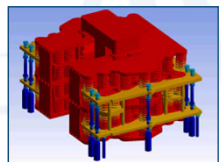
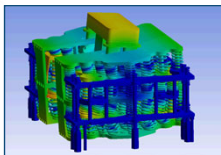
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**Most Significant Risk: Off-Axis Modes**

- Several Off-Axis Resonant Modes in addition to the Primary Mode
  - 7 Unique body combination
  - 6 Degrees of Freedom per body
  - 42 Degrees of Freedom!**
- Each Degree of Freedom creates its own Mode at a specific frequency
- Three Factors determine each Natural Frequency
  - Mass
  - Stiffness
  - Rotational Inertia




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**Most Significant Risk: Off-Axis Modes**

- RAM5 & OmniRAM includes 2 sensors that shutdown the Resonator if off-axis limit is exceeded
- These sensors cannot capture all off-axis modes!
- Outcomes of operating too near Off-Axis Modes
  1. Resonator will shut down
  2. Resonator will fail
  3. Vessel or Vessel holder will fail




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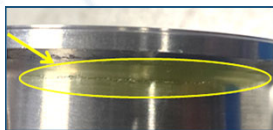
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**Most Significant Risk: Off-Axis Modes**

- Outcomes of operating too near Off-Axis Modes
  1. Resonator will shut down
  2. Resonator will fail
  3. Vessel or Vessel holder will fail

Date/Time	Message	Ack	Res	ID
8/29/2024 1:57:05 PM	Service In Error			
8/29/2024 1:57:05 PM	Off axis acceleration #1			




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### Pedestal Design Envelope

- Because of the complexity in designing for RAM environments, Resodyn recommends the use of Resodyn Vessels, Vessel Holders, and MIC Holders
- Resodyn provides limited support for Customer Designed Vessels and Holders in the form of a design envelope
- Three parameters set the design envelope; limits provided in the Modal Test Report

Design Parameter
Starting Frequency
Max Acceleration
Avoid Off-Axis Modes



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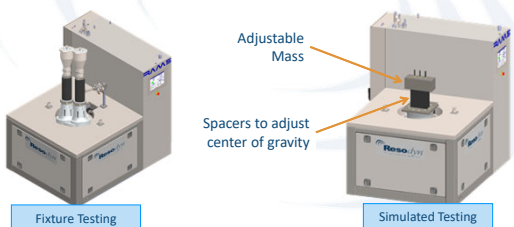
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### Generating the Modal Test Report

- Limits for each design parameter is determined by testing each fixture on the RAM it will operate with
- Simulated system with adjustable mass and center of gravity used when fixturing is not available



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### Reading the Modal Test Report

- Typical Modal Test Report includes:
  - Results from vessel specific testing

Test	Class	Vessel	Mass	Mode #	Mode F	Mode A
1	1	CO4000	300	1	100	0.00
2	1	CO4000	300	2	150	0.00
3	1	CO4000	300	3	200	0.00
4	1	CO4000	300	4	250	0.00
5	1	CO4000	300	5	300	0.00
6	1	CO4000	300	6	350	0.00
7	1	CO4000	300	7	400	0.00
8	1	CO4000	300	8	450	0.00
9	1	CO4000	300	9	500	0.00
10	1	CO4000	300	10	550	0.00
11	1	CO4000	300	11	600	0.00
12	1	CO4000	300	12	650	0.00
13	1	CO4000	300	13	700	0.00
14	1	CO4000	300	14	750	0.00
15	1	CO4000	300	15	800	0.00
16	1	CO4000	300	16	850	0.00
17	1	CO4000	300	17	900	0.00
18	1	CO4000	300	18	950	0.00
19	1	CO4000	300	19	1000	0.00
20	1	CO4000	300	20	1050	0.00
21	1	CO4000	300	21	1100	0.00
22	1	CO4000	300	22	1150	0.00
23	1	CO4000	300	23	1200	0.00
24	1	CO4000	300	24	1250	0.00
25	1	CO4000	300	25	1300	0.00
26	1	CO4000	300	26	1350	0.00
27	1	CO4000	300	27	1400	0.00
28	1	CO4000	300	28	1450	0.00
29	1	CO4000	300	29	1500	0.00
30	1	CO4000	300	30	1550	0.00
31	1	CO4000	300	31	1600	0.00
32	1	CO4000	300	32	1650	0.00
33	1	CO4000	300	33	1700	0.00
34	1	CO4000	300	34	1750	0.00
35	1	CO4000	300	35	1800	0.00
36	1	CO4000	300	36	1850	0.00
37	1	CO4000	300	37	1900	0.00
38	1	CO4000	300	38	1950	0.00
39	1	CO4000	300	39	2000	0.00
40	1	CO4000	300	40	2050	0.00
41	1	CO4000	300	41	2100	0.00
42	1	CO4000	300	42	2150	0.00
43	1	CO4000	300	43	2200	0.00
44	1	CO4000	300	44	2250	0.00
45	1	CO4000	300	45	2300	0.00
46	1	CO4000	300	46	2350	0.00
47	1	CO4000	300	47	2400	0.00
48	1	CO4000	300	48	2450	0.00
49	1	CO4000	300	49	2500	0.00
50	1	CO4000	300	50	2550	0.00
51	1	CO4000	300	51	2600	0.00
52	1	CO4000	300	52	2650	0.00
53	1	CO4000	300	53	2700	0.00
54	1	CO4000	300	54	2750	0.00
55	1	CO4000	300	55	2800	0.00
56	1	CO4000	300	56	2850	0.00
57	1	CO4000	300	57	2900	0.00
58	1	CO4000	300	58	2950	0.00
59	1	CO4000	300	59	3000	0.00
60	1	CO4000	300	60	3050	0.00
61	1	CO4000	300	61	3100	0.00
62	1	CO4000	300	62	3150	0.00
63	1	CO4000	300	63	3200	0.00
64	1	CO4000	300	64	3250	0.00
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76	1	CO4000	300	76	3850	0.00
77	1	CO4000	300	77	3900	0.00
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80	1	CO4000	300	80	4050	0.00
81	1	CO4000	300	81	4100	0.00
82	1	CO4000	300	82	4150	0.00
83	1	CO4000	300	83	4200	0.00
84	1	CO4000	300	84	4250	0.00
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86	1	CO4000	300	86	4350	0.00
87	1	CO4000	300	87	4400	0.00
88	1	CO4000	300	88	4450	0.00
89	1	CO4000	300	89	4500	0.00
90	1	CO4000	300	90	4550	0.00
91	1	CO4000	300	91	4600	0.00
92	1	CO4000	300	92	4650	0.00
93	1	CO4000	300	93	4700	0.00
94	1	CO4000	300	94	4750	0.00
95	1	CO4000	300	95	4800	0.00
96	1	CO4000	300	96	4850	0.00
97	1	CO4000	300	97	4900	0.00
98	1	CO4000	300	98	4950	0.00
99	1	CO4000	300	99	5000	0.00
100	1	CO4000	300	100	5050	0.00



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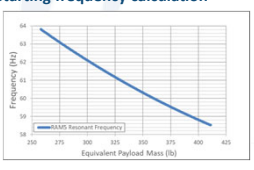
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### Reading the Modal Test Report

- Typical Modal Test Report includes:
  - Results from vessel specific testing
  - Starting frequency calculation



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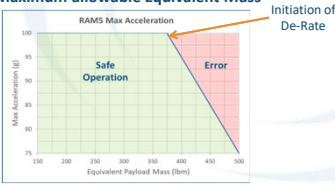
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### Reading the Modal Test Report

- Typical Modal Test Report includes:
  - Results from vessel specific testing
  - Starting frequency calculation
  - Maximum allowable Equivalent Mass



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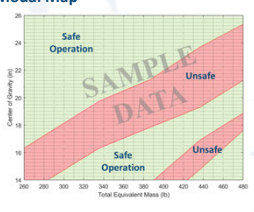
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### Reading the Modal Test Report

- Typical Modal Test Report includes:
  - Results from vessel specific testing
  - Starting frequency calculation
  - Maximum allowable Equivalent Mass
  - Modal Map



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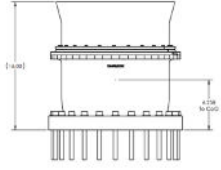

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### Reading the Modal Test Report

- **Typical Modal Test Report includes:**
  - Results from vessel specific testing
  - Starting frequency calculation
  - Maximum allowable Equivalent Mass
  - Modal Map
  - Vessel specific CoG information

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### How to Measure: Mass

- **Tooling Mass:** Mass of fixed equipment attached to the payload plate
- **Coupled Material Mass:** Portion of Mix & Coolant mass that doesn't absorb energy
- **Uncoupled Material Mass:** Portion of Mix & Coolant mass that absorbs energy
- **Equivalent Payload Mass:** Tooling Mass + Coupled Mix Mass

**Example 1**



**Example 2**

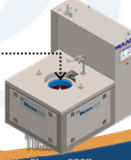


**Tooling**

- Pedestal
- Vessel Holder
- Vessel / MIC Vessels
- Lids / MIC Hoppers
- RTDs / Fittings
- Fasteners

**Does Not Include**

- Mix Material
- Coolant
- Hoses / Cables



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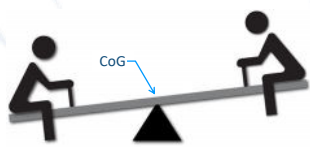
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### How to Measure: Center of Gravity (CoG)

- Point around which mass of a rigid body is balanced
  - Found for each component and the system

$$CoG = \frac{\sum Mass_i * Distance}{Mass_{Total}}$$


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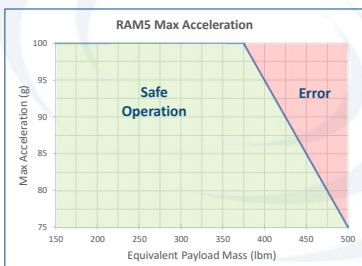
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### Example: Maximum Acceleration

334 lb equivalent mass requires no acceleration de-rate

Equivalent Payload Mass = 334 lb



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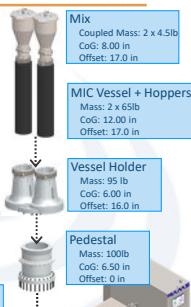
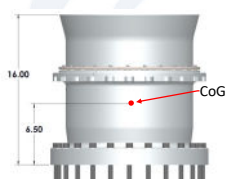
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### Example: Calculating Center of Gravity

Center of Gravity & Offset Calculated for each component



$$CoG = \frac{\sum Mass_i * (CoG_i + Offset_i)}{Mass_{Total}} = 20.17$$



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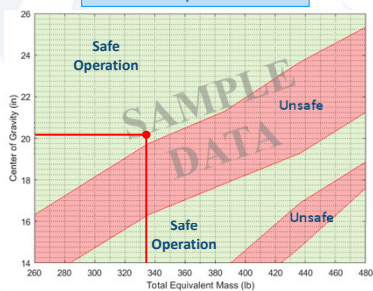
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### Example: Avoiding Off-Axis Modes

Mass and Center of Gravity Compared To the Modal Map

Equivalent Payload Mass = 334 lb  
Center of Gravity = 20.17 in



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Thank you for your time  
and attention.



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